

Optimizing Power Utilization In Electric Vehicle Charging Stations Through 75 Bus Energy Management System

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Abstract: - The rapid growth of electric vehicle (EV) adoption necessitates efficient power utilization strategies within charging stations. This thesis presents an innovative approach to optimizing power utilization in EV charging stations through the implementation of a 75-bus energy management system. The system leverages a combination of renewable energy sources, including solar and wind power, alongside grid energy to enhance the sustainability and efficiency of EV charging processes. Key components of the system include intelligent scheduling for vehicle charging and discharging, accurate state-of-charge (SOC) estimation for vehicle batteries, and the management of bi-directional power flows between vehicles and the grid.

Through extensive simulations and real-world data analysis, this research demonstrates significant improvements in energy efficiency and cost savings. The 75-bus system effectively balances energy supply and demand, reduces reliance on grid power during peak times, and mitigates the variability and uncertainty associated with renewable energy sources. Additionally, the study explores the potential of using advanced forecasting techniques and load scheduling to further enhance system performance.

Keywords: - Electric Vehicle Charging Stations, Power Utilization Optimization, 75-Bus Energy Management System, Renewable Energy Integration, Intelligent Charging Scheduling, State-of-Charge Estimation, Bi-directional Power Flow, Smart Grid Technology, Energy Efficiency

I. INTRODUCTION

Carbon dioxide emissions have increased due to the widespread use of fossil fuels from rapidly depleting conventional energy sources, which eventually results in the glasshouse gas effect. The escalating effects of glasshouse gases from conventional internal combustion engines (IC) paved the way for the fast growth of pollution-free electric vehicles in the automotive industry (EV). Professor Sibrandus Stratingh of the University of Groningen in the Netherlands created a small scale electric car in 1835 after Anyos Jedlik created an electric motor for a model car in 1828. The car was powered by non-rechargeable batteries. General Motors President Rick Wagoner unveiled the "Impact," a two-seat electric vehicle, later that year at the Los Angeles Auto Show. The Mitsubishi i-MiEV was released in Japan in 2009, and this marked the beginning of the modern era of highway electric vehicles. In 2008, Tesla Motors released the Tesla Roadster in California. With the introduction of competitive EVs by Nissan, BMW, Renault, Ford, Volkswagen, and Chevrolet, there are now eight available EVs.

Since traction batteries can handle high power and energy demands while occupying little space and weight, they are frequently used in electric vehicles. In order to advance EV battery technology, a lot of research is being done [Young et al., 2013]. Until recently, only lead acid batteries were used in electric vehicles. Nickel batteries, which have a high power density and dependability, have largely replaced lead acid batteries in EVs because

of their low specific energy and short cycle life. On the other hand, nickel batteries generate a lot of heat at high temperatures and have a high rate of self-discharge. Lithium batteries are now preferred because of their high power density, light weight, and small size. Low specific energy, subpar thermal capabilities, and chemical leakage are all overcome. Korth Pereira Ferraz et al. (2018); Chen et al. (2012). Additionally, the wide operating temperature range, low self-discharge rate, long life cycle, and fast charging capability all contribute to its increased use in the EV industry. Lithium titanate and lithium ferrophosphate batteries are the most popular types of lithium batteries. The lithium ferrophosphate battery has superior thermal stability when fully charged and is unlikely to be inadvertently overcharged. The lithium titanate battery can be quickly recharged and has a wide operating temperature range.

The use of EVs is constrained by their inability to charge batteries, high cost, and brief lifespan [Beretta, 2010; Chan and Chau, 1997]. A 240 V or 400 V outlet is necessary for the AC Level 2 charging method, which is a semi-fast charging method. Using 208/415 volts, AC Level 3 charging is a three-phase fast charging technique. The charging station's DC fast charging method is designed for both public and commercial use. On-board and off-board chargers are the two different types of EV battery chargers. A single off-board charger is installed, but the entire vehicle has an on-board charger. For on-board chargers, there are limitations in terms of size, weight, available space, and price (Aggeler et al., 2010; Haghbin et al., 2010). This charger can be integrated with electric vehicle motor drives, with the motor winding serving as filter inductors or an isolated transformer, to get around these restrictions (Thiringer et

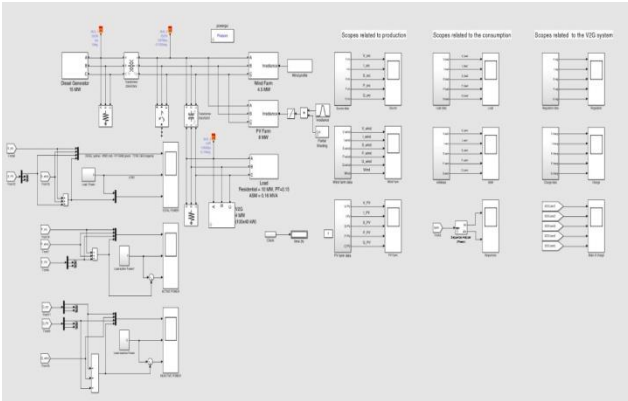


Fig.2 Proposed Model

Figure2 also shows the output of the proposed model like total power generation in the model and active and reactive power. This model basically designs for 24x60x60 power generation for the charging station. Figure 3 shows the proposed model of 75 bus system. In this different model is connected to each other.

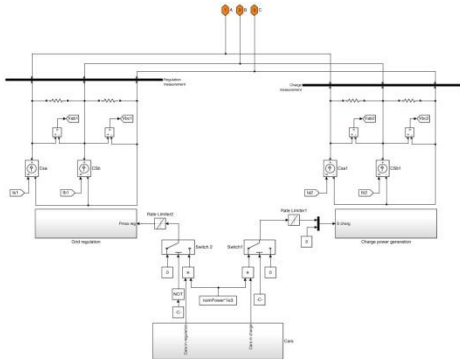


Fig.3 Model of Proposed Bus System

Figure 3 is show power management of charging station also show charging station section where we are charge 5 EV's in one time.

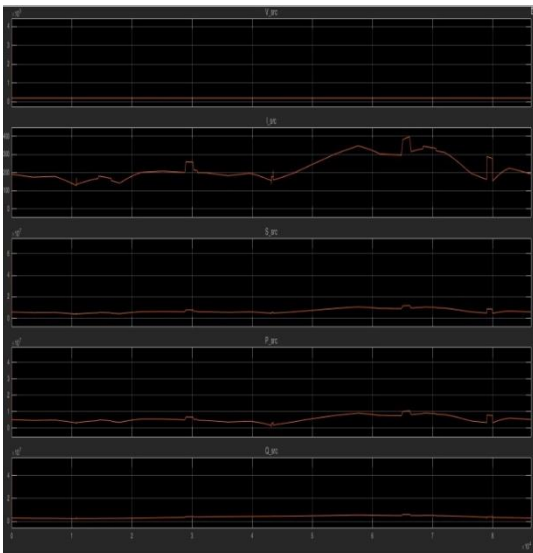


Fig.4 Wave form of voltage, current and power

Figure 4 shows the result waveform of voltage, current and power. In this figure first waveform of voltage source is a rms value, second waveform of current source of rms value, third waveform of electrical switches and then last waveform of power.

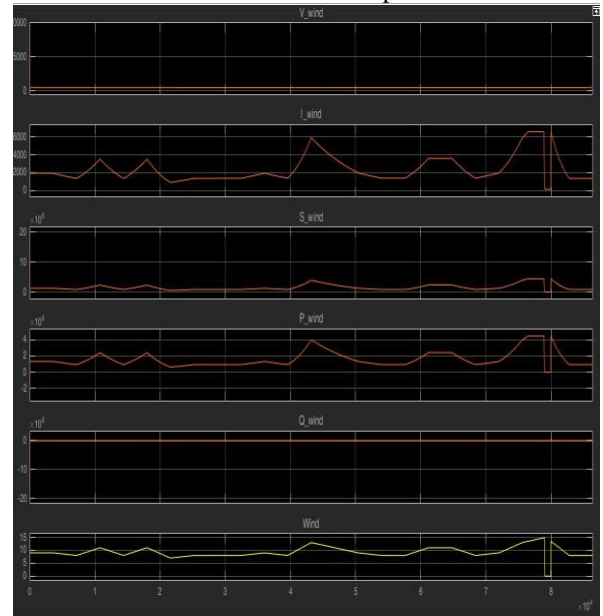


Fig.5 Waveform of Wind voltage, current and wind power

Figure 5 shows the waveform of voltage, current, power, electrical switches and wind power.

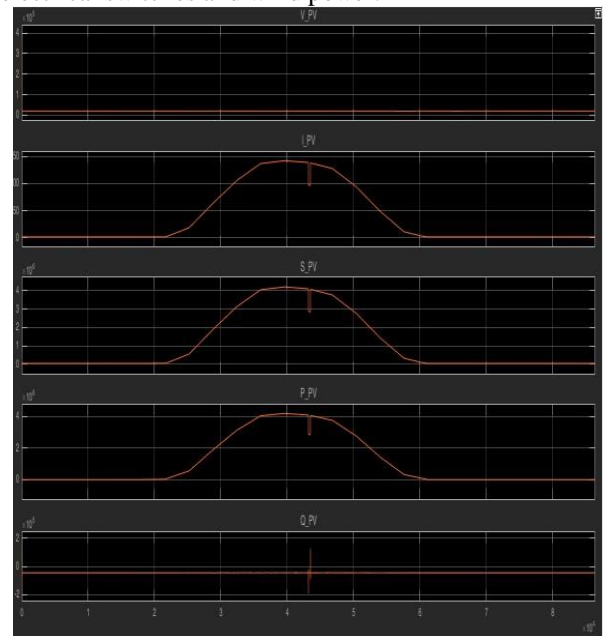


Fig.6 waveform of solar cell of voltage, current and power

Figure 6 shows the result waveform of photovoltaic cell of voltage, current and power with respect to time.

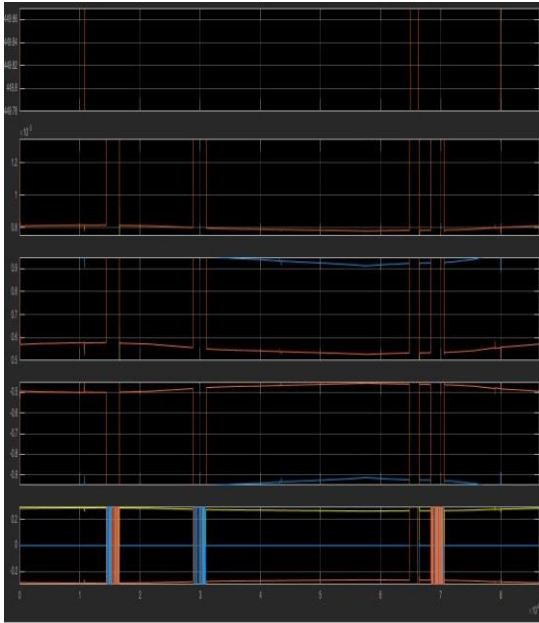


Fig.7 output of state of charge

Figure 7 shows result output waveform of state of charge. Battery controller waveform.

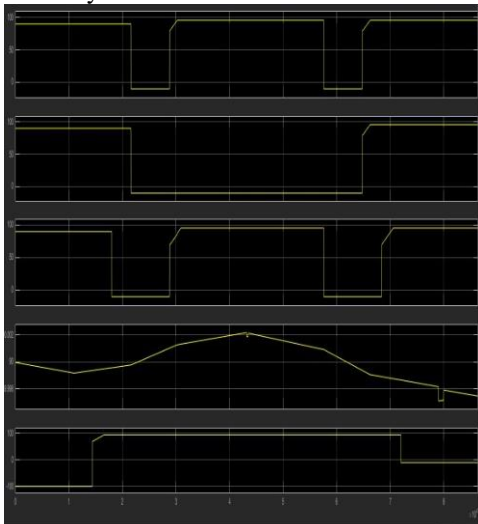


Fig.8 wave forms of active power

Figure 8 shows result waveform of active power of total generation power.

IV. CONCLUSION

The development of the hybrid renewable energy system is ongoing. Voltage and current waveforms are seen in MATLAB simulations. These systems are more dependable and stable than single-source systems, according to the simulation results. It is used in grid-connected systems as well as off-grid areas. In an Indian 75-bus power system, the optimal power flow problem is resolved using differential evolution. Differential evolution has a number of advantages over other contemporary heuristics, including modelling adaptability, certain and quick convergence, and reduced computational time. It is possible to draw the conclusion

that this charging station, with the provided control, is capable of utilising different energy sources very efficiently and providing consistent and affordable charging to EVs.

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